# UPSC Civil Services Main 2005 - Mathematics Linear Algebra

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**Question 1(a)** Find the values of k for which the vectors (1, 1, 1, 1), (1, 3, -2, k), (2, 2k - 2, -k - 2, 3k - 1) and (3, k - 2, -3, 2k + 1) are linearly independent in  $\mathbb{R}^4$ .

Solution. The given vectors are linearly independent if the matrix

$$\begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 3 & -2 & k \\ 2 & 2k - 2 & -k - 2 & 3k - 1 \\ 3 & k + 2 & -3 & 2k + 1 \end{pmatrix}$$

is non-singular.

Now

$$\begin{vmatrix} 1 & 1 & 1 & 1 \\ 1 & 3 & -2 & k \\ 2 & 2k-2 & -k-2 & 3k-1 \\ 3 & k+2 & -3 & 2k+1 \end{vmatrix} = \begin{vmatrix} 1 & 0 & 0 & 0 \\ 1 & 2 & -3 & k-1 \\ 2 & 2k-4 & -k-4 & 3k-3 \\ 3 & k-1 & -6 & 2k-2 \end{vmatrix} = \begin{vmatrix} 2 & -3 & k-1 \\ 2k-4 & -k-4 & 3k-3 \\ k-1 & -6 & 2k-2 \end{vmatrix}$$
$$= \begin{vmatrix} 2 & -3 & k-1 \\ 2k-4 & -k-4 & 3k-3 \\ k-5 & 0 & 0 \end{vmatrix} = (k-5)[-9k+9+(k-1)(k+4)] \neq 0$$

Clearly  $(k-5)[-9k+9+(k-1)(k+4)] = 0 \Leftrightarrow k = 1, 5$ . Thus the vectors are linearly independent when  $k \neq 1, 5$ .

1 For more information log on www.brijrbedu.org. Copyright By Brij Bhooshan @ 2012. **Question 1(b)** Let  $\mathcal{V}$  be the vector space of polynomials in x of degree  $\leq n$  over  $\mathbb{R}$ . Prove that the set  $\{1, x, x^2, \ldots, x^n\}$  is a basis for  $\mathcal{V}$ . Extend this so that it becomes a basis for the set of all polynomials in x.

**Solution.**  $\{1, x, x^2, \ldots, x^n\}$  are linearly independent over  $\mathbb{R}$  — If  $a_0 + a_1 x + \ldots + a_n x^n = 0$ where  $a_i \in \mathbb{R}, 0 \le i \le n$ , then we must have  $a_i = 0$  for every *i* because the non-zero polynomial  $a_0 + a_1 x + \ldots + a_n x^n$  can have at most *n* roots in  $\mathbb{R}$  whereas  $a_0 + a_1 x + \ldots + a_n x^n = 0$ for every  $x \in \mathbb{R}$ .

Every polynomial in x of degree  $\leq n$  is clearly a linear combination of  $1, x, x^2, \ldots, x^n$  with coefficients from  $\mathbb{R}$ . Thus  $\{1, x, x^2, \ldots, x^n\}$  is a basis for  $\mathcal{V}$ .

We shall show that  $\mathscr{S} = \{1, x, x^2, \dots, x^n, x^{n+1}, \dots\}$  is a basis for the space of all polynomials.

(i) Linear Independence: Let  $\{x^{i_1}, \ldots, x^{i_r}\}$  be a finite subset of  $\mathscr{S}$ . Let  $n = \max\{i_1, \ldots, i_r\}$ , then  $\{x^{i_1}, \ldots, x^{i_r}\}$  being a subset of the linearly independent set  $\{1, x, x^2, \ldots, x^n\}$  is linearly independent, which shows the linear independence of  $\mathscr{S}$ .

(ii) Let f be any polynomial. If degree of f is m, then f is a linear combination of  $\{1, x, x^2, \ldots, x^m\}$ , which is a subset of  $\mathcal{S}$ . Thus  $\mathcal{S}$  is a basis of  $\mathcal{W}$ , the space of all polynomials over  $\mathbb{R}$ .

Question 2(a) Let **T** be a linear transformation on  $\mathbb{R}^3$  whose matrix relative to the standard basis of  $\mathbb{R}^3$  is  $\begin{pmatrix} 2 & 1 & -1 \\ 1 & 2 & 2 \\ 3 & 3 & 4 \end{pmatrix}$ . Find the matrix of **T** relative to the basis  $\mathscr{B} = \{(1, 1, 1), (1, 1, 0), (0, 1, 1)\}$ .

Solution. Let the vectors of the given basis be  $\mathbf{v_1}, \mathbf{v_2}, \mathbf{v_3}$ .  $(\mathbf{T}(\mathbf{v_1}), \mathbf{T}(\mathbf{v_2}), \mathbf{T}(\mathbf{v_3})) = \begin{pmatrix} 2 & 1 & -1 \\ 1 & 2 & 2 \\ 3 & 3 & 4 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 3 & 0 \\ 5 & 3 & 4 \\ 10 & 6 & 7 \end{pmatrix}$ . If  $(a, b, c) = \alpha \mathbf{v_1} + \beta \mathbf{v_2} + \gamma \mathbf{v_3}$ , then  $\alpha + \beta = a, \alpha + \beta + \gamma = b, \alpha + \gamma = c$  therefore

 $a = a - b + c, \beta = b - c, \gamma = b - a.$  Consequently

$$\begin{aligned} \mathbf{T}(\mathbf{v_1}) &= 7\mathbf{v_1} - 5\mathbf{v_2} + 3\mathbf{v_3} \\ \mathbf{T}(\mathbf{v_1}) &= 6\mathbf{v_1} - 3\mathbf{v_2} + 0\mathbf{v_3} \\ \mathbf{T}(\mathbf{v_1}) &= 3\mathbf{v_1} - 3\mathbf{v_2} + 4\mathbf{v_3} \end{aligned}$$

This shows that the matrix of **T** with respect to given basis  $\mathscr{B}$  is  $\begin{pmatrix} 7 & 6 & 3 \\ -5 & -3 & -3 \\ 3 & 0 & 4 \end{pmatrix}$ 

Question 2(b) If S is a skew-Hermitian matrix, then show that  $\mathbf{A} = (\mathbf{I} + \mathbf{S})(\mathbf{I} - \mathbf{S})^{-1}$  is a unitary matrix. Show that a unitary matrix A can be expressed in the above form provided -1 is not an eigenvalue of A.

**Solution.** See related results of question 2(a) year 1989.

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Question 2(c) Reduce the quadratic form

$$6x_1^2 + 3x_2^2 + 3x_3^2 - 4x_1x_2 - 4x_2x_3 + 4x_1x_3$$

to a sum of squares. Also find the corresponding linear transformation, index and signature.

#### Solution.

$$\begin{aligned} \mathcal{Q}(x_1, x_2, x_3) &= 6x_1^2 + 3x_2^2 + 3x_3^2 - 4x_1x_2 - 4x_2x_3 + 4x_1x_3 \\ &= 6[x_1^2 - \frac{2}{3}x_1x_2 + \frac{2}{3}x_1x_3 + \frac{1}{9}x_2^2 + \frac{1}{9}x_3^2 - \frac{2}{9}x_2x_3] \\ &+ \frac{7}{3}x_2^2 + \frac{7}{3}x_3^2 - \frac{8}{3}x_2x_3 \\ &= 6[x_1 - \frac{1}{3}x_2 + \frac{1}{3}x_3]^2 + \frac{7}{3}[x_2 - \frac{4}{7}x_3]^2 + \frac{33}{21}x_3^2 \end{aligned}$$

Put  $X_1 = x_1 - \frac{1}{3}x_2 + \frac{1}{3}x_3, X_2 = x_2 - \frac{4}{7}x_3, X_3 = x_3$ , so that

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 & \frac{1}{3} & -\frac{1}{7} \\ 0 & 1 & \frac{4}{7} \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 \\ X_3 \end{pmatrix}$$
(1)

and  $Q(x_1, x_2, x_3)$  is transformed to  $6X_1^2 + \frac{7}{3}X_2^2 + \frac{33}{21}X_3^2$ . Let

$$\begin{pmatrix} X_1 \\ X_2 \\ X_3 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{6}}Z_1 \\ \sqrt{\frac{3}{7}}Z_2 \\ \sqrt{\frac{7}{11}}Z_3 \end{pmatrix}$$

then  $\mathcal{Q}(x_1, x_2, x_3)$  is transformed to  $Z_1^2 + Z_2^2 + Z_3^2$ , which is its canonical form. Thus  $\mathcal{Q}(x_1, x_2, x_3)$  is positive definite. The Index of  $\mathcal{Q}(x_1, x_2, x_3) =$  Number of positive squares in its canonical form = 3. The signature of  $\mathcal{Q}(x_1, x_2, x_3) =$  Number of positive squares - the number of negative squares in its canonical form = 3.

The required linear transformation which transforms  $Q(x_1, x_2, x_3)$  to sums of squares is given by (1), and the linear transformation which transforms it to its canonical form is given by

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 & \frac{1}{3} & -\frac{1}{7} \\ 0 & 1 & \frac{4}{7} \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{6}} & 0 & 0 \\ 0 & \sqrt{\frac{3}{7}} & 0 \\ 0 & 0 & \sqrt{\frac{7}{11}} \end{pmatrix} \begin{pmatrix} Z_1 \\ Z_2 \\ Z_3 \end{pmatrix}$$

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